High-performance Distributed Object Computing with Real-time CORBA

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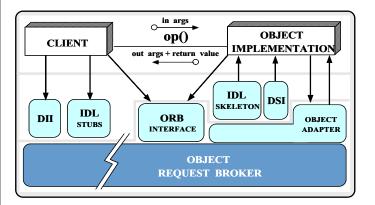
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Motivation

- Typical state of affairs today is the "Distribution Crisis"
 - Computers and networks get faster and cheaper
 - Communication software gets slower, buggier, more expensive
- Accidental complexity is one source of problems, e.g.,
- Incompatible software infrastructures
- Continuous rediscovery and reinvention of core concepts and components
- Inherent complexity is another source of problems
 - e.g., latency, partial failures, partitioning, causal ordering, etc.

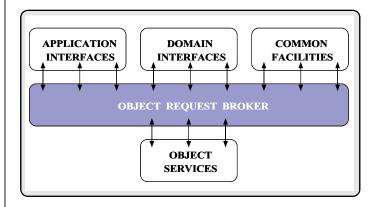
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Candidate Solution: CORBA

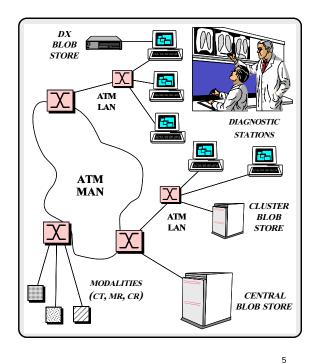


- Goals
- 1. Simplify development of distributed applications
- 2. Provide flexible foundation for higher-level services

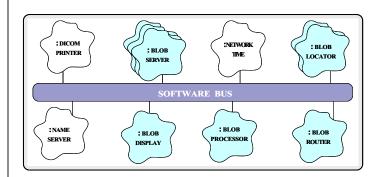
OMA Reference Model Interface Categories



Example 1: Distributed Medical Imaging



Distributed Objects in Medical Imaging

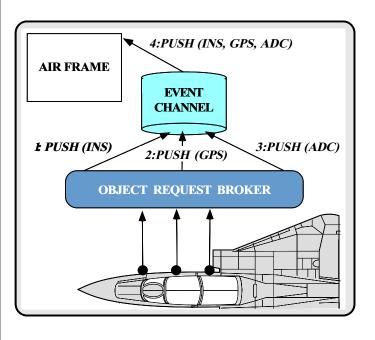


• "Blob" == Binary Large OBject

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Example 2: Real-time Avionics



Observations

- CORBA is well-suited for certain communication requirements and certain network environments
 - e.g., request/response or oneway messaging over low-speed Ethernet or Token Ring
- However, current CORBA implementations exhibit high overhead for other types of requirements and environments
 - e.g., bandwidth-intensive and delay-sensitive applications over high-speed networks
- Performance limitations will ultimately impede adoption of CORBA

Key Research Questions

- "Can CORBA be used for performance-sensitive applications on high-speed networks?"
 - Goal is to determine this empirically
- "What are the strategic optimizations for Gigabit CORBA"?
 - Goal is to maintain strict CORBA compliance
- "What changes are required to provide Realtime CORBA?"
- Goal is to provide end-to-end QoS guarantees

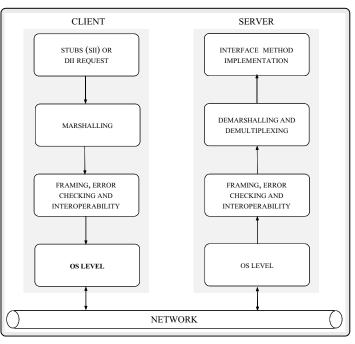
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Pinpointing CORBA Overhead

- Presentation layer overhead
 - e.g., typed and untyped data
- Data manipulation and data copying overhead
 - e.g., message management
- Demultiplexing and operation dispatching overhead
 - e.g., layered and de-layered demultiplexing
- OS/network/protocol integration
 - e.g., ATM/host adapters, resource reservation and scheduling

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General Path of CORBA Requests

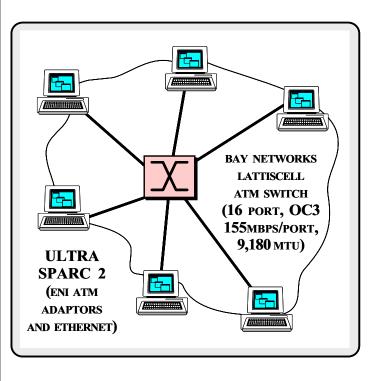


Experimental Setup

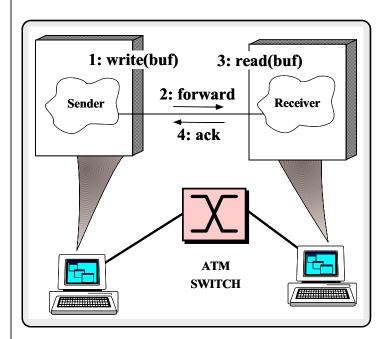
- Enhanced version of TTCP
 - TTCP measures end-to-end data/request transfer
 - Enhanced version compares C, ACE C++ wrappers, Orbix 2.0.1 and VisiBroker 2.0, and Blob Streaming
- Parameters varied
 - 100 Mbytes of typed data
 - ▶ Types included scalars, floats, structs, and sequences
 - Sender buffer sizes ranged from 1K to 128K
 - Socket queues were 8k (default) and 64k (maximum)
 - Network was 155 Mbps ATM and "loopback"

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Network/Host Environment



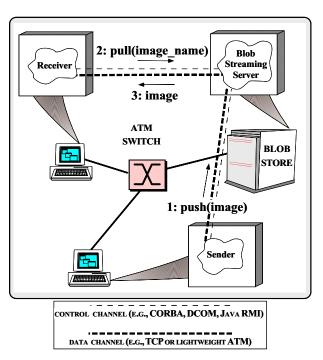
TTCP Configuration for C and ACE C++ Wrappers



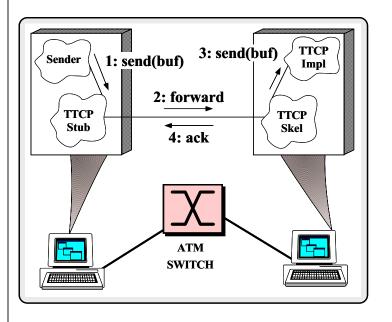
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Blob Streaming System Architecture

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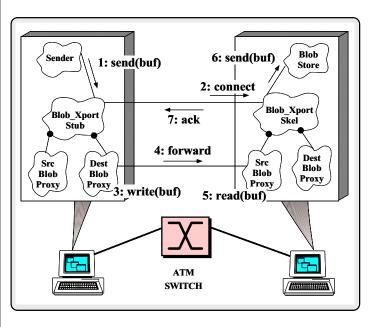
TTCP Configuration for CORBA Implementation



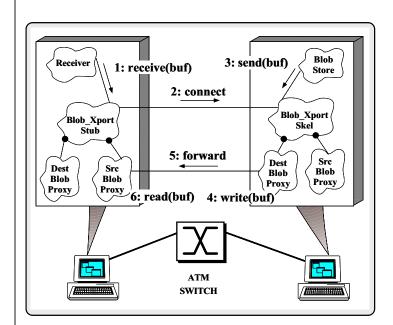
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TTCP Configuration for Blob Streaming (Push Model)

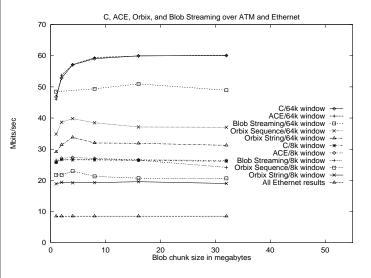


TTCP Configuration for Blob Streaming (Pull Model)

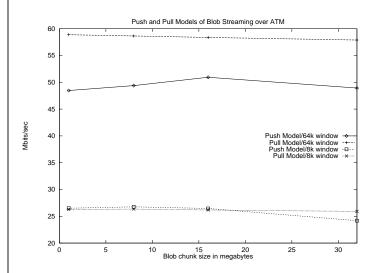


Push Model Performance over ATM and Ethernet

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Pull Model Performance over ATM



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High-Cost Functions

- C and ACE C++ Tests
 - Transferring 100 Mbytes with 1 Mbyte buffers

Test	%Time	#Calls	Name
C sockets	93.9	112	write
(sender)	3.6	110	read
C sockets	93.2	13,085	read
(receiver)	4.5	102	write
ACE C++ wrapper	94.4	112	write
(sender)	3.2	110	read
ACE C++ wrapper	93.9	12,984	read
(receiver)	5.6	102	write

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• Orbix String and Sequence

Test	%Time	#Calls	Name
Orbix Sequence (sender)	53.5	127	write
	35.1	223	read
	7.3	1,108	memcpy
Orbix Sequence (receiver)	84.6 12.4 3.2	12,846 1,064 101	read memcpy write
Orbix String (sender)	45.0	127	write
	35.1	223	read
	10.8	1,315	strlen
	6.0	1,108	memcpy
Orbix String (receiver)	70.7	12,443	read
	16.1	2,142	strlen
	10.0	1,064	memcpy
	3.0	101	write

High-Cost Functions (cont'd)

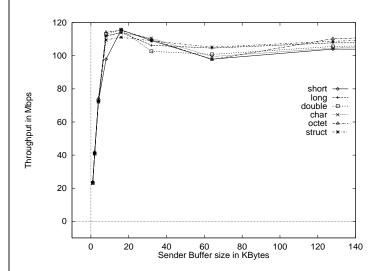
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High-Cost Functions (cont'd)

Blob Streaming

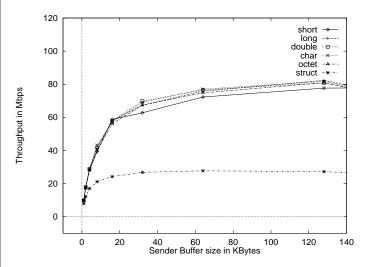
Test	%Time	#Calls	Name
BlobStreaming (sender)	48.8 44.8 1.3	327 232 2,055	write read memcpy
BlobStreaming (receiver)	77.2 16.4 1.4	12,546 12,734 102	read memcpy write

C/C++ Remote Data Transfer Results

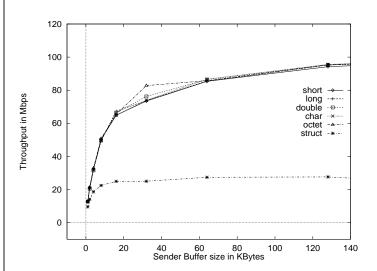


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Orbix Remote Data Transfer Results



VisiBroker Remote Data Transfer Results



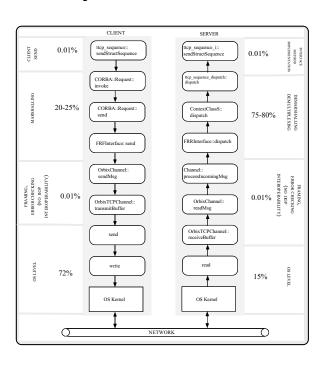
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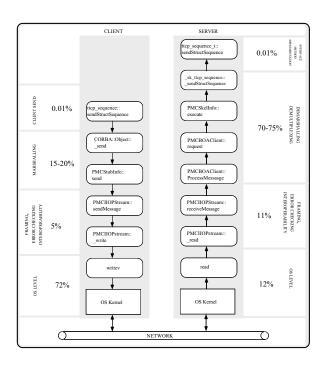
Analysis of Orbix Overhead

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Analysis of VisiBroker Overhead



Summary of Throughput Results

• For bytestreams

- VisiBroker performed > 80% cf C/C++ versions
- Orbix performed 70% cf C/C++ versions

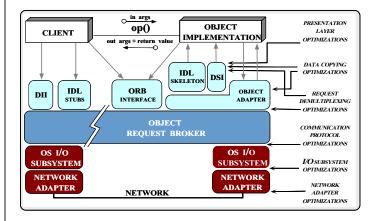
• For scalars and floats

- Remote: 75-80% cf C/C++ versions
- Loopback: Orbix performed 65-68% cf C/C++ versions, VisiBroker achieved similar throughput for large sender buffer sizes

• For structures

- Remote: 31% cf C/C++ versions
- Loopback: 16% cf C/C++ versions

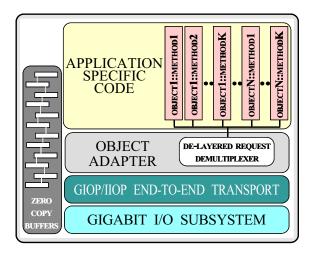
Gigabit CORBA Optimizations



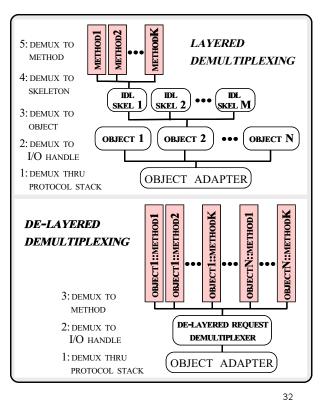
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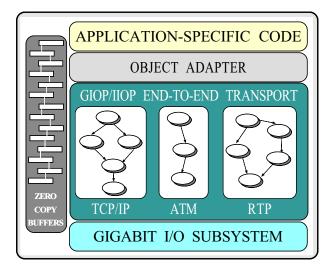
Real-time CORBA



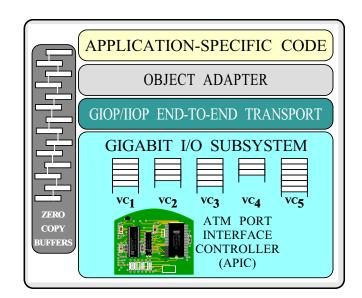
Demultiplexing Optimizations



Multi-Protocol Support



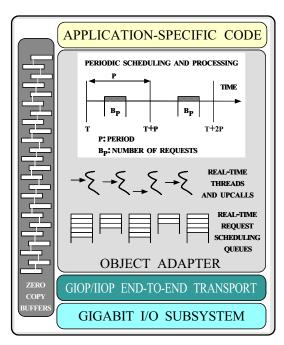
I/O Subsystem Optimizations



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Real-time Scheduling Optimizations

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Concluding Remarks

- CORBA is a promising architecture for distributed computing
- Conventional CORBA implementations are not tuned for high-performance or real-time systems
 - Note, low-speed networks often hide performance overhead
- Ultimately, an integrated approach is the best solution
- Optimizations must be applied at multiple layers

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- e.g., network/OS/protocol/ORB