

CORBA for Telecom Systems Fact or Fiction?

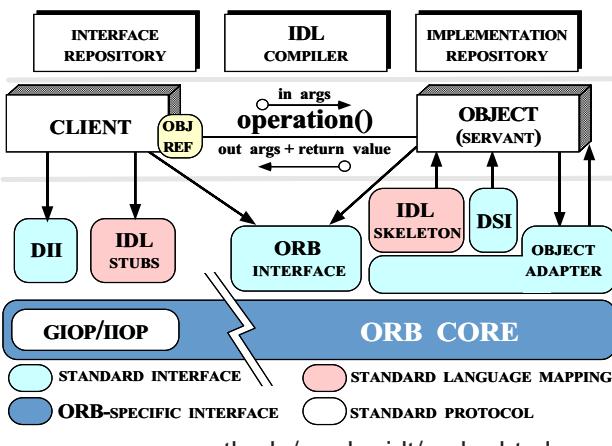
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Candidate Solution: CORBA



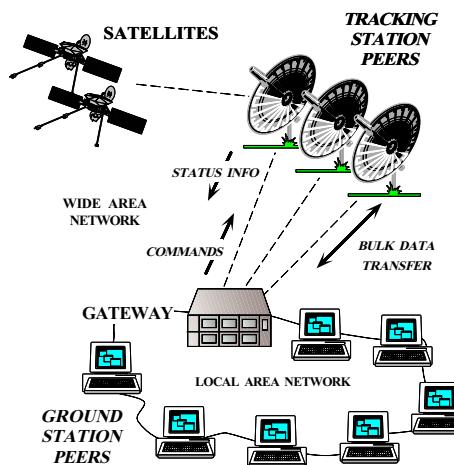
- **Goals of CORBA**
 - Simplify distribution by automating
 - * Object location & activation
 - * Parameter marshaling
 - * Demultiplexing
 - * Error handling
 - Provide foundation for higher-level services

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Problem: Lack of Real-time Middleware for Telecom



- Many telecom applications require QoS guarantees
 - e.g., call-processing, network management, wireless systems
- Building these applications manually is hard
- Existing middleware doesn't support QoS effectively
 - e.g., CORBA, DCOM, DCE
- Solutions must be *integrated*

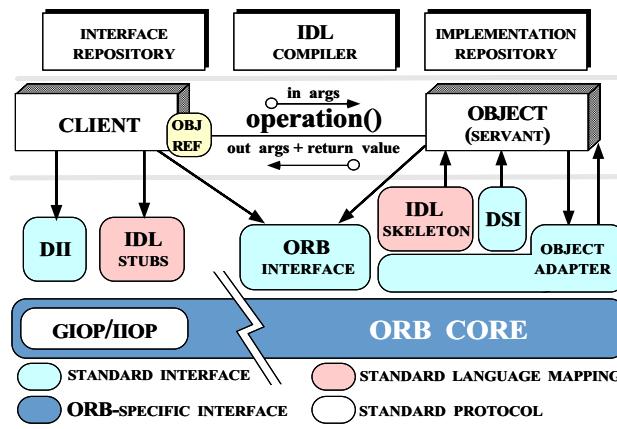
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Caveat: Limitations of CORBA for Telecom Systems

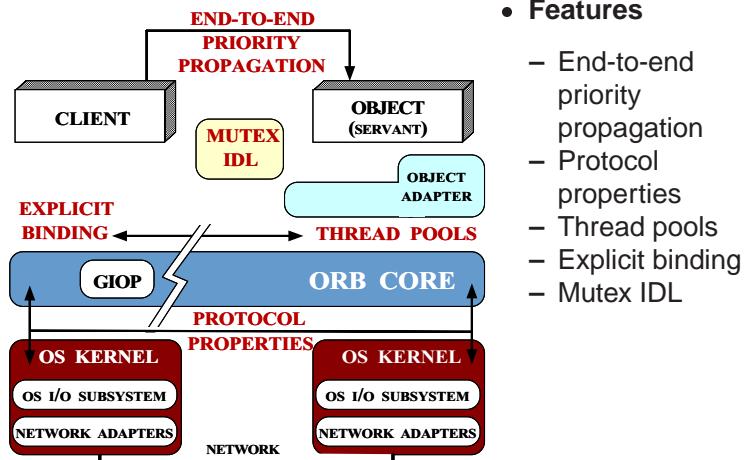


- **Limitations**
 - Lack of QoS specifications
 - Lack of QoS enforcement
 - Lack of real-time programming features
 - Lack of performance optimizations

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Overview of the Joint Real-time CORBA Submission



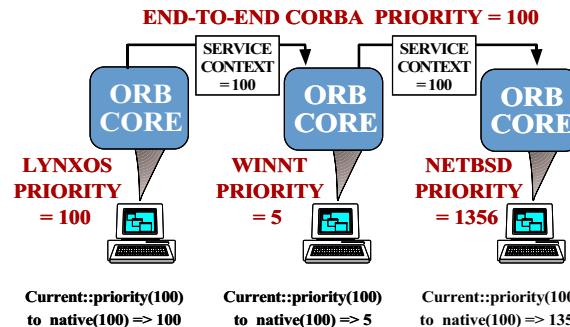
- Features

- End-to-end priority propagation
- Protocol properties
- Thread pools
- Explicit binding
- Mutex IDL

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End-to-End Priority Propagation



- Features

- Priorities can propagate end-to-end
 - * Supports heterogeneous RTOS priority mappings
 - * Supports priority inheritance
 - Servers can also dictate priority

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Protocol Properties

```
interface ProtocolProperties {};
typedef struct {
    IOP::ProfileId protocol_type;
    ProtocolProperties
        orb_protocol_properties;
    ProtocolProperties
        transport_protocol_properties;
} Protocol;
typedef sequence <Protocol> ProtocolList;

interface TCPProtocolProperties
    : ProtocolProperties
{
    attribute long send_buffer_size;
    attribute long recv_buffer_size;
    attribute boolean keep_alive;
    attribute boolean dont_route;
    attribute boolean no_delay;
};
```

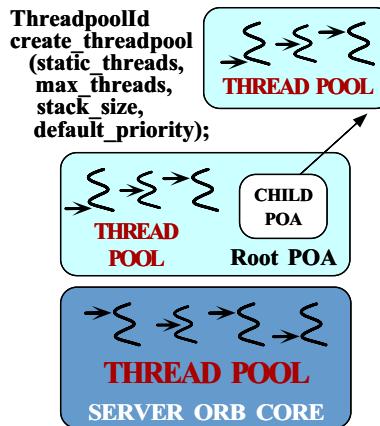
- Features

- Select and configure communication protocols
 - * e.g., TCP socket options
- Supports *ORB protocol* and *transport protocol* configuration
- Ordering in *ProtocolList* indicates preferences

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Thread Pools



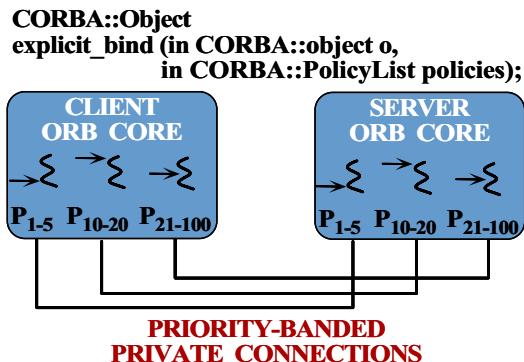
- Features

- Pre-allocate threads and thread attributes
 - * Stacksize
 - * Static threads
 - * Maximum threads
 - * Default priority
- Applicable at both the *ORB* and *POA* level

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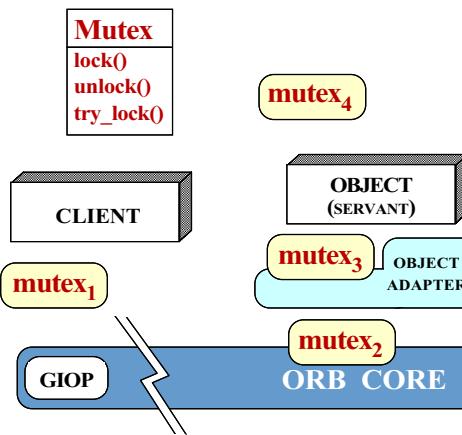
Explicit Binding



- **Features**

- Enables pre-establishment of connections
 - * Priority-banded connections
 - * Private connections
 - * Protocol policies

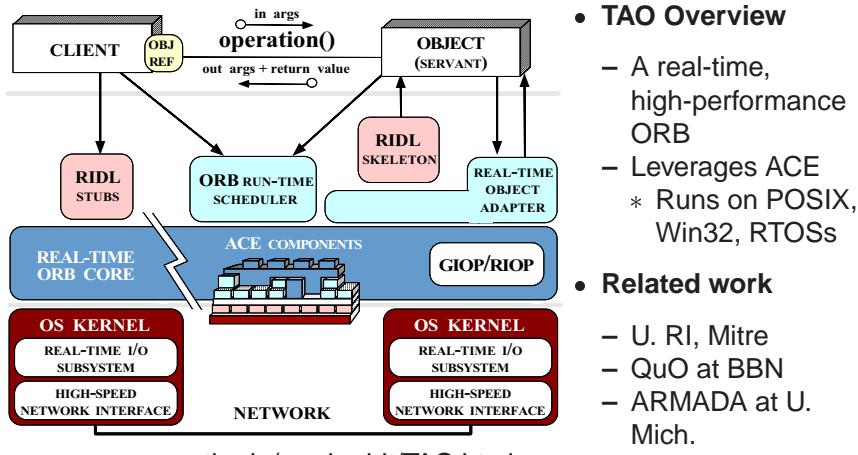
Mutex IDL



- **Features**

- A portable Mutex API
 - * e.g., lock, unlock, try_lock
- Necessary to ensure consistency between ORB and application synchronizers
- Locality constrained

The ACE ORB (TAO)



- **TAO Overview**

- A real-time, high-performance ORB
- Leverages ACE
 - * Runs on POSIX, Win32, RTOSs

- **Related work**

- U. RI, Mitre
- QuO at BBN
- ARMADA at U. Mich.

Concluding Remarks

- Developers of distributed, real-time telecom applications confront common challenges
 - e.g., service initialization and distribution, error handling, flow control, scheduling, event demultiplexing, concurrency control, persistence, fault tolerance
- Successful developers apply *design patterns*, *frameworks*, and *components* to resolve these challenges
- ORBs are an effective way to achieve reuse of distributed telecom software components
- The next generation of ORBs will provide much better support for real-time QoS

Web URLs for Additional Information

- **Real-time CORBA:** www.cs.wustl.edu/~schmidt/RT-ORB.ps.gz
- **Integrated ORB and OS I/O subsystem architecture:**
www.cs.wustl.edu/~schmidt/RT-middleware.ps.gz
- **More information on TAO:** www.cs.wustl.edu/~schmidt/TAO.html
- **TAO Event Channel:** www.cs.wustl.edu/~schmidt/JSAC-98.ps.gz
- **TAO static scheduling:** www.cs.wustl.edu/~schmidt/TAO.ps.gz
- **TAO dynamic scheduling:**
www.cs.wustl.edu/~schmidt/dynamic.ps.gz